

Fixed Point Theorems for Functions satisfying Implicit Relations in Generalized b-Metric spaces

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(Received June 13, 2019, Accepted September 1, 2019)

Abstract

The aim of this paper is to present some fixed point results for functions satisfying implicit relations in two complete and compact Generalized b-Metric spaces

1 Introduction and Preliminaries

Mustafa and Sims [10] introduced the concept of G-metric spaces as a generalization of a metric space. Since then, several interesting results for existence of fixed point in G-metric spaces have been obtained (see [2-4],[7], [10–11]).

On the other hand, V. Papa et al. proved some fixed point theorems for functions satisfying an implicit relations in metric spaces and G-metric spaces (see [13-18]).

Key words and phrases: Fixed point, Implicit relations, Generalized b-Metric spaces.

AMS (MOS) Subject Classifications: 37C25, 54H25.

ISSN 1814-0432, 2020, <http://ijmcs.future-in-tech.net>

The notion of b-metric space was introduced by Czerwik [8]. Many authors studied fixed point theorems in b-metric spaces (see [1],[6],[9],[12],[19]). Recently, Aghajani et al. [5] generalized the concept of b-metric spaces by using the notions of b-metric spaces and G-metric spaces, which is called G_b -metric spaces and they discussed some properties and common fixed point results of G_b -metric.

The aim of this paper is to present some fixed point results for functions satisfying implicit relations in two complete and compact Generalized b-Metric spaces.

We recall some basic definitions and results following [5].

Definition 1.1. *Let X be a non empty set and $\delta \geq 1$ be a given real number. Suppose that a mapping $G : X \times X \times X \rightarrow \mathbb{R}^+$ satisfies the following axioms:*

- (G_b1) $G(x, y, z) = 0$ if $x = y = z$,
- (G_b2) $0 < G(x, x, y)$, for all $x, y \in X$ with $x \neq y$,
- (G_b3) $G(x, x, y) \leq G(x, y, z)$, for all $x, y, z \in X$, with $z \neq y$,
- (G_b4) $G(x, y, z) = G(p(x, z, y))$ where p is a permutation of x, y, z (symmetry),
- (G_b5) $G(x, y, z) \leq \delta(G(x, a, a) + G(a, y, z))$, for all $x, y, z, a \in X$, (triangle inequality).

Then the function G is called a generalized b-metric (G_b -metric on X) and the pair (X, G) is called a generalized b-metric space.

Proposition 1.2. *Let (X, G) be a G_b -metric space. Then for any x, y, z and $a \in X$,*

- (1) if $G(x, y, z) = 0$, then $x = y = z$,
- (2) $G(x, y, z) \leq \delta(G(x, x, y) + G(x, x, z))$,
- (3) $G(x, y, y) \leq 2\delta G(y, x, x)$,
- (4) $G(x, y, z) \leq \delta(G(x, a, z) + G(a, y, z))$.

Definition 1.3. *Let (X, G) be a G_b -metric space, and (x_n) be a sequence of points of X . We say that (x_n) is G_b -convergent to x if for any $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that $G(x, x_n, x_m) < \varepsilon$, for all $n, m \geq n_0$.*

Proposition 1.4. *Let (X, G) be a G_b -metric space. Then the following are equivalent:*

- (1) (x_n) is G-convergent to x ,
- (2) $G(x_n, x_n, x) \rightarrow 0$, as $n \rightarrow \infty$,
- (3) $G(x_n, x, x) \rightarrow 0$, as $n \rightarrow \infty$,

Definition 1.5. Let (X, G) be a G_b -metric space. A sequence (x_n) is called G_b -Cauchy if given $\varepsilon > 0$, there is $n_o \in N$ such that $G(x_n, x_m, x_l) < \varepsilon$, for all $n, m, l \geq n_o$.

Proposition 1.6. Let X be a G_b -metric space. Then the following are equivalent:

- (1) the sequence $\{x_n\}$ is G_b -Cauchy.
- (2) for any $\varepsilon > 0$, there exists $n_0 \in N$ such that $G(x_n, x_m, x_m) < \varepsilon$, for all $m, n \geq n_0$.

Definition 1.7. Let (X, G) and (X^*, G^*) be G_b -metric space and let $h : (X, G) \rightarrow (X^*, G^*)$ be a function. Then h is said to be G_b - continuous at a point $a \in X$, if given $\varepsilon > 0$, there exists $\delta > 0$ such that $x, y \in X, G(a, x, y) < \delta$ implies $G^*(h(a), h(x), h(y)) < \varepsilon$.

Definition 1.8. A G_b -metric space (X, G) is said to be G_b -complete if every G_b -Cauchy sequence in (X, G) is G_b -convergent in (X, G) .

Definition 1.9. A G_b -metric space (X, G) is said to be a compact G_b -metric space if it is G_b -complete and G_b -totally bounded.

2 Main Results

Let π be the set of all upper semi-continuous in each coordinate variable $h : \mathbb{R}^+ \times \mathbb{R}^+ \times \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}$ such that, if $h(\mu^2, \mu\nu, 0, 0) \leq 0$ or $h(\mu^2, 0, \mu\nu, 0) \leq 0$ or $h(\mu^2, 0, 0, \mu\nu) \leq 0$ for all $\mu, v \geq 0$, then $\mu \leq \frac{1}{4\delta^3}v$.

Example 2.1. $h(t_1, t_2, t_3, t_4) = t_1 - \frac{1}{4\delta^3} \max(t_2, t_3, t_4)$.

Example 2.2. $h(t_1, t_2, t_3, t_4) = t_1 - \frac{1}{4\delta^3}t_2 - \frac{1}{4\delta^3} \max(t_3, t_4)$.

Example 2.3. $h(t_1, t_2, t_3, t_4) = t_1 - \frac{1}{4\delta^3}t_2 - \frac{1}{4\delta^3}t_3 - \frac{1}{4\delta^3}t_4$.

Theorem 2.1. Let (X, G_1) and (Y, G_2) be complete G_b - metric spaces, and $H : X \rightarrow Y, K : Y \rightarrow X$ be functions satisfying the following conditions:

$$g(G_2^2(H\xi, HKr_1, HKr_2), G_2(r_1, HKr_1, HKr_2)G_2(r_1, r_2, H\xi), G_2(r_1, r_2, H\xi)G_1(\xi, Kr_1, Kr_2), G_1(\xi, Kr_1, Kr_2)G_2(r_1, HKr_1, HKr_2)) \leq 0 \tag{2.1}$$

$$g(G_1^2(Kr_1, Kr_2, KH\xi), G_1(\xi, \xi, KH\xi)G_1(\xi, Kr_1, Kr_2), G_1(\xi, Kr_1, Kr_2)G_2(r_1, r_2, H\xi), \quad (2.2)$$

$$G_2(r_1, r_2, H\xi)G_1(\xi, \xi, KH\xi)) \leq 0$$

for all ξ in X and r_1, r_2 in Y , $h \in \pi$. Then KH and HK have unique fixed points z in X and w in Y respectively. Moreover, $Hz = w$ and $Kw = z$.

Proof. Define the sequences (ξ_n) in X , and (r_n) in Y by $\xi_n = (KH)^n \xi$, $r_n = H(KH)^{n-1} \xi$, for $n = 1, 2, \dots$. We suppose that $\xi_n \neq \xi_{n+1}$ and $r_n \neq r_{n+1}$ for all n . Applying the inequality (2.1) and property π , we have

$$g(G_2^2(H\xi_{n-1}, HKr_n, HKr_n), G_2(r_n, HKr_n, HKr_n)G_2(r_n, r_n, H\xi_{n-1}),$$

$$G_2(r_n, r_n, H\xi_{n-1})G_1(\xi_{n-1}, Kr_n, Kr_n), G_1(\xi_{n-1}, Kr_n, Kr_n)G_2(r_n, HKr_n, HKr_n)) \leq 0$$

$$g(G_2^2(r_n, r_{n+1}, r_{n+1}), 0, 0, G_1(\xi_{n-1}, \xi_n, \xi_n)G_2(r_n, r_{n+1}, r_{n+1})) \leq 0$$

and it follows that

$$G_2^2(r_n, r_{n+1}, r_{n+1}) \leq \frac{1}{4\delta^3} G_1(\xi_{n-1}, \xi_n, \xi_n) G_2(r_n, r_{n+1}, r_{n+1})$$

$$G_2(r_n, r_{n+1}, r_{n+1}) \leq \frac{1}{4\delta^3} G_1(\xi_{n-1}, \xi_n, \xi_n) \quad (2.3)$$

Similarly, applying the inequality (2.2),

$$g(G_1^2(Kr_n, Kr_n, KH\xi_n), G_1(\xi_n, \xi_n, \xi_{n+1})G_1(\xi_n, Kr_n, Kr_n),$$

$$G_1(\xi_n, Kr_n, Kr_n)G_2(r_n, r_n, H\xi_n), G_2(r_n, r_n, H\xi_n)G_1(\xi_n, \xi_n, \xi_{n+1})) \leq 0$$

$$g(G_1^2(\xi_n, \xi_n, \xi_{n+1}), G_1(\xi_n, \xi_n, \xi_{n+1})G_1(\xi_n, \xi_n, \xi_n), G_1(\xi_n, \xi_n,$$

$$\xi_n)G_2(r_n, r_n, r_{n+1}), G_2(r_n, r_n, r_{n+1})G_1(\xi_n, \xi_n, \xi_{n+1})) \leq 0$$

Using property π and the Proposition (1.2), we have

$$G_1^2(\xi_n, \xi_n, \xi_{n+1}) \leq \frac{1}{4\delta^3} G_2(r_n, r_n, r_{n+1}) G_1(\xi_n, \xi_n, \xi_{n+1})$$

$$\frac{1}{2\delta} G_1(\xi_n, \xi_{n+1}, \xi_{n+1}) \leq G_1(\xi_n, \xi_n, \xi_{n+1}) \leq \frac{1}{4\delta^3} G_2(r_n, r_n, r_{n+1}) \leq \frac{1}{2\delta^2} G_2(r_n, r_{n+1}, r_{n+1})$$

$$G_1(\xi_n, \xi_{n+1}, \xi_{n+1}) \leq \frac{1}{\delta} G_2(r_n, r_{n+1}, r_{n+1}) \quad (2.4)$$

Now it follows from the inequalities (2.3) and (2.4) that

$$G_1(\xi_n, \xi_{n+1}, \xi_{n+1}) \leq \frac{1}{4\delta^4} G_1(\xi_{n-1}, \xi_n, \xi_n).$$

Hence, by induction we get

$$G_1(\xi_n, \xi_{n+1}, \xi_{n+1}) \leq \left(\frac{1}{4\delta^4}\right)^n G_1(\xi, \xi_1, \xi_1), \text{ for } n = 1, 2, \dots \quad (2.5)$$

So (ξ_n) and (r_n) are G_b -Cauchy sequences with limits z in X and w in Y . Using the inequality (2.1), we have

$$\begin{aligned} &g(G_2^2(Hz, HKr_{n-1}, HKr_{n-1}), G_2(r_{n-1}, HKr_{n-1}, HKr_{n-1})G_2(r_{n-1}, r_{n-1}, Hz), \\ &G_2(r_{n-1}, r_{n-1}, Hz)G_1(z, Kr_{n-1}, Kr_{n-1}), G_1(z, Kr_{n-1}, Kr_{n-1})G_2(r_{n-1}, HKr_{n-1}, HKr_{n-1})) \leq 0 \\ &g(G_2^2(Hz, r_n, r_n), G_2(r_{n-1}, r_n, r_n)G_2(r_{n-1}, r_{n-1}, Hz), \\ &G_2(r_{n-1}, r_{n-1}, Hz)G_1(z, \xi_{n-1}, \xi_{n-1}), G_1(z, \xi_{n-1}, \xi_{n-1})G_2(r_{n-1}, r_n, r_n)) \leq 0. \\ &g(G_2^2(Hz, w, w), 0, 0, 0) \leq 0, \end{aligned}$$

it follows that $G_2(Hz, w, w) = 0$, hence $w = Hz$. Using the inequality (2.2), we have

$$\begin{aligned} &g(G_1^2(Kw, Kw, KH\xi_{n-1}), G_1(\xi_{n-1}, \xi_{n-1}, KH\xi_{n-1})G_1(\xi_{n-1}, Kw, Kw), \\ &G_1(\xi_{n-1}, Kw, Kw)G_2(w, w, H\xi_{n-1}), G_2(w, w, H\xi_{n-1})G_1(\xi_{n-1}, \xi_{n-1}, KH\xi_{n-1})) \leq 0. \\ &g(G_1^2(Kw, Kw, \xi_n), G_1(\xi_{n-1}, \xi_{n-1}, KH\xi_{n-1})G_1(\xi_{n-1}, Kw, Kw), \\ &G_1(\xi_{n-1}, Kw, Kw)G_2(w, w, H\xi_{n-1}), G_2(w, w, H\xi_{n-1})G_1(\xi_{n-1}, \xi_{n-1}, KH\xi_{n-1})) \leq 0. \end{aligned}$$

Letting $n \rightarrow \infty$, we get $g(G_1^2(Kw, Kw, \xi_n), 0, 0, 0) \leq 0$, and it follows that $z = Kw$. Thus $KHz = Kw = z$, $HKw = Hz = w$, and so KH and HK have a fixed points z and w respectively. Suppose that KH and HK have other fixed points z_1 in X and w_1 in Y respectively. Using property π and the inequality (2.1), we have

$$\begin{aligned} &g(G_2^2(Hz, HKw_1, HKw_1), G_2(w_1, HKw_1, HKw_1)G_2(w_1, w_1, Hz), \\ &G_2(w_1, w_1, Hz)G_1(z, Kw_1, Kw_1), G_1(z, Kw_1, Kw_1)G_2(w_1, HKw_1, HKw_1)) \leq 0 \\ &g(G_2^2(HKw, HKw_1, HKw_1), 0, G_2(w_1, w_1, w)G_1(Kw, Kw_1, Kw_1), 0) \leq 0, \\ &g(G_2^2(w, w_1, w_1), 0, G_2(w_1, w_1, w)G_1(Kw, Kw_1, Kw_1), 0) \leq 0, \end{aligned}$$

it follows that $G_2^2(w, w_1, w_1) \leq \frac{1}{4\delta^3} G_1(Kw, Kw_1, Kw_1) G_2(w_1, w_1, w)$,

$$G_2(w, w_1, w_1) \leq \frac{1}{4\delta^3} G_1(Kw, Kw_1, Kw_1). \quad (2.6)$$

Using the property π and the inequality (2.2), we have

$$g(G_1^2(KHKw, KHKw, KHKw_1), G_1(Kw_1, Kw_1, KHSw_1)G_1(Kw_1, KHKw, KHKw),$$

$$G_1(Kw_1, KHKw, KHKw)G_2(HKw, HKw, HKw_1)G_2$$

$$(HKw, HKw, HKw_1)G_1(Kw_1, Kw_1, KHKw_1)) \leq 0,$$

$$g(G_1^2(Kw, Kw, Kw_1), 0, G_1(Kw_1, Kw, Kw)G_2(w, w, w_1), 0) \leq 0$$

which implies that $G_1^2(Kw, Kw, Kw_1) \leq \frac{1}{4\delta^3} G_2(w, w, w_1) G_1(Kw, Kw, Kw_1)$,

$$G_1(Kw, Kw, Kw_1) \leq \frac{1}{4\delta^3} G_2(w, w, w_1), \quad (2.7)$$

by using the Proposition (1.2), we get,

$$\frac{1}{2\delta} G_1(Kw, Kw_1, Kw_1) \leq G_1(Kw, Kw, Kw_1) \leq \frac{1}{4\delta^3} G_2(w, w, w_1) \leq \frac{1}{2\delta^3} G_2(w, w_1, w_1)$$

$$G_1(Kw, Kw_1, Kw_1) \leq \frac{1}{\delta^2} G_2(w, w_1, w_1). \quad (2.8)$$

Now it follows from the inequalities (2.6) and (2.8) that

$$G_2(w, w_1, w_1) \leq \frac{1}{4\delta^3} G_1(Sw, Sw_1, Sw_1) < \frac{1}{4\delta^5} G_2(w, w_1, w_1) < G_2(w, w_1, w_1)$$

and so $w = w_1$. Hence w must be a unique fixed point of HK . Now $HKz_1 = z_1$ implies $HKHz_1 = Hz_1$ and so $Hz_1 = w$. Thus $z = KH z = Kw = KH z_1 = z_1$, z is a unique fixed point of KH . \square

Now, we prove an analogous result for compact G-metric spaces.

Let π^* be the set of all functions $h : \mathbb{R}^+ \times \mathbb{R}^+ \times \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}$ such that, if $h(\mu^2, \mu\nu, 0, 0) < 0$ or $h(\mu^2, 0, \mu\nu, 0) < 0$ or $h(\mu^2, 0, 0, \mu\nu) < 0$ for all $\mu, \nu \geq 0$, then $\mu \leq \frac{1}{2\delta} \nu$.

Theorem 2.2. *Let (X, G_1) and (Y, G_2) be compact G-metric spaces, and H be a continuous function of X into Y and let S be a continuous function of Y into X satisfying the following conditions:*

$$g(G_2^2(Hx, HSy_1, HSy_2), G_2(y_1, HSy_1, HSy_2)G_2(y_1, y_2, Hx), G_2(y_1, y_2, Hx)G_1(x, Sy_1, Sy_2), \quad (2.9)$$

$$G_1(x, Sy_1, Sy_2)G_2(y_1, HSy_1, HSy_2) < 0, \text{ with } x \neq Sy_1, \text{ and } x \neq Sy_2$$

$$g(G_1^2(Sy_1, Sy_2, SHx), G_1(x, x, SHx)G_1(x, Sy_1, Sy_2), G_1(x, Sy_1, Sy_2)G_2(y_1, y_2, Hx)),$$

(2.10)

$$G_2(y_1, y_2, Hx)G_1(x, x, SHx) < 0, \text{ with } y_1 \neq Hx, y_2 \neq Hx.$$

for all x in X and y_1, y_2 in Y , $g \in \pi^*$. Then SH has a unique fixed point z in X and HS has a unique fixed point $w \in Y$. Moreover, $Hw = z$ and $Sw = z$.

Proof. Let $\psi : X \rightarrow R^+$ defined by $\psi(x) = G_1(x, SHx, SHx)$ be G -continuous on X . Since X is compact, there exists a point u in X such that $\psi(u) = G_1(u, SHu, SHu) = \min\{G_1(x, SHx, SHx); x \in X\}$. Now suppose that $Hu \neq HSHu$. Then $u \neq SHu$. Put $y_1 = y_2 = Hu, x = Sy = SHu$ in the inequality (2.10). We have

$$g(G_1^2(SHu, SHu, SHSHu), G_1(SHu, SHu, SHSHu)G_1(SHu, SHu, SHu),$$

$$G_1(SHu, SHu, SHu)G_2(Hu, Hu, HSHu), G_2(Hu, Hu, HSHu)G_1(SHu, SHu, SHSHu)) < 0$$

$$g(G_1^2(SHu, SHu, SHSHu), 0, 0, G_2(Hu, Hu, HSHu)G_1(SHu, SHu, SHSHu)) < 0.$$

Using the condition of π^* and Proposition(1.2) we have

$$G_1^2(SHu, SHu, SHSHu) < \frac{1}{2\delta}G_2(Hu, Hu, HSHu)G_1(SHu, SHu, SHSHu)$$

$$G_1(SHu, SHu, SHSHu) < \frac{1}{2\delta}G_2(Hu, Hu, HSHu) < G_2(Hu, HSHu, HSHu)$$

Put $y_1 = y_2 = Hu, x = u$ in the inequality (2.9). We have

$$g(G_2^2(Hu, HSHu, HSHu), G_2(Hu, HSHu, HSHu)G_2(Hu, Hu, Hu),$$

$$G_2(Hu, Hu, Hu)G_1(u, SHu, SHu), G_1(u, SHu, SHu)G_2(Hu, HSHu, HSHu)) < 0$$

$$g(G_2^2(Hu, HSHu, HSHu), 0, 0, G_1(u, SHu, SHu)G_2(Hu, HSHu, HSHu)) < 0$$

But, using condition π^*

$$G_2^2(Hu, HSHu, HSHu) < \frac{1}{2\delta}G_1(u, SHu, SHu)G_2(Hu, HSHu, HSHu),$$

$$G_2(Hu, HSHu, HSHu) < \frac{1}{2\delta}G_1(u, SHu, SHu)$$

$$\frac{1}{2\delta}G_1(SHu, SHSHu, SHSHu) \leq G_1(SHu, SHu, SHSHu) < \frac{1}{2\delta}G_1(u, SH, SHu) \\ G_1(SHu, SHSHu, SHSHu) < G_1(u, SHu, SHu).$$

Hence $\psi(SHu) < \psi(u)$, which is a contradiction. So $HSHu = Hu$. If $Hu = w$ and $Sw = z$, then $SH(SHu) = S(HSHu) = SHu = Sw = z$, and $w = Hu = HS(Hu) = H(SHu) = Hz$. Thus, $Sw = z$ is a fixed point of SH and $Hz = w$ is a fixed point of HS . \square

Suppose that SH has a another fixed point z_1 . Then applying the inequality (2.10), we have

$$g(G_1^2(SHz, SHz, SHz_1), G_1(z_1, z_1, SHz_1)G_1(z_1, z, z), \\ G_1(z_1, z, z)G_2(Hz, Hz, Hz_1), G_2(Hz, Hz, Hz_1)G_1(z_1, z_1, SHz_1)) < 0. \\ g(G_1^2(z, z, z_1), G_1(z_1, z_1, SHz_1)G_1(z_1, z, z), G_1(z_1, z, z)G_2(Hz, Hz, Hz_1), \\ 2(Hz, Hz, Hz_1)G_1(z_1, z_1, SHz_1)) < 0.$$

Using condition π^*

$$G_1^2(z, z, z_1) < \frac{1}{2\delta}G_2(Hz, Hz, Hz_1)G_1(z_1, z, z) \\ G_1(z, z, z_1) < \frac{1}{2\delta}G_2(Hz, Hz, Hz_1).$$

Applying the inequality (2.9) and using condition π^* we obtain,

$$g(G_2^2(Hz, HSHz_1, HSHz_1), G_2(Hz_1, HSHz_1, HSHz_1)G_2(Hz_1, 1, Hz), \\ G_2(Hz_1, Hz_1, Hz)G_1(z, SHz_1, SHz_1), \\ G_1(z, SHz_1, SHz_1)G_2(Hz_1, HSHz_1, HSHz_1)) < 0 \\ g(G_2^2(Hz, Hz_1, Hz_1), 0, G_2(Hz_1, Hz_1, Hz)G_1(z, z_1, z_1), 0) < 0, \\ G_2^2(Hz, Hz_1, Hz_1) < \frac{1}{2\delta}G_1(z, z_1, z_1)G_2(Hz_1, Hz_1, Hz), \\ \frac{1}{2\delta}G_2(Hz_1, Hz, Hz) \leq G_2(Hz, Hz_1, Hz_1) < \frac{1}{2\delta}G_1(z, z_1, z_1).$$

It follows that $G_1(z, z, z_1) < \frac{1}{2\delta}G_1(z, z_1, z_1) \leq G_1(z, z, z_1)$, which is a contradiction and so z must be a unique fixed point. Similarly, w is a unique fixed point of HS .

Acknowledgment. This project was supported by the Deanship of Scientific Research at Sattam Bin Abdulaziz University, KSA, under the research project No. 2015/01/4152.

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