

# On functional equations related to generalized Jordan derivations in rings

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## Abstract

In this paper, we generalize the notions of Jordan derivation and generalized Jordan derivation to Jordan  $(f, g)$ -derivation and generalized Jordan  $(f, g)$ -derivation, respectively. Moreover, we investigate additive mappings satisfying some functional equations becomes Jordan  $(f, g)$ -derivation and generalized Jordan  $(f, g)$ -derivation.

## 1 Introduction

A derivation on a ring  $R$  is an additive mapping  $D$ , which maps a ring  $R$  into itself satisfying the product rule  $D(xy) = D(x)y + xD(y)$  for all  $x$  and  $y$  in  $R$ . In 1957, Posner [2] proved two theorems, namely: (1) In a prime ring of characteristics not 2, if the iterate of two derivations is a derivation, then one of them is zero; (2) If  $D$  is a derivation of a prime ring such that, for all elements  $a$  of the ring,  $aD(a) - D(a)a$  is central, then either the ring is commutative or  $D$  is zero. An additive mapping  $D$  which maps a ring  $R$  into itself is called a Jordan derivation if  $D(x^2) = D(x)x + xD(x)$  holds for all  $x$  in  $R$ . It is straight forward to see that every derivation on a ring is a Jordan derivation but the converse need not be true in general. Herstein

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[3] proved that any Jordan derivation on a prime ring of characteristic not 2 is a derivation. Bresar [8] extended this result to semiprime rings. In 1991, Bresar [9] introduced the notion of generalized derivations in rings as follows: an additive mapping  $F : R \rightarrow R$  is said to be a generalized derivation if there exists a derivation  $D : R \rightarrow R$  such that  $F(xy) = F(x)y + xD(y)$  holds for all  $x, y$  in  $R$ . An additive mapping  $F : R \rightarrow R$  is said to be a generalized Jordan derivation if there exists a Jordan derivation  $D : R \rightarrow R$  such that  $F(x^2) = F(x)x + xD(x)$  holds for all  $x, y$  in  $R$ . Obviously, every generalized derivation is a generalized Jordan derivation but there exists generalized Jordan derivation which is not generalized derivation. Ashraf and Rehman [6] showed that in a 2-torsion free ring, which has a commutator nonzero divisor, every generalized Jordan derivation on  $R$  is a generalized derivation. In 2007, Vukman [4] proved that every generalized Jordan derivation on a 2-torsion free semiprime ring is a generalized derivation. An additive mapping  $x \mapsto x^*$  on a ring  $R$  is called an involution if  $(x^*)^* = x$  and  $(xy)^* = y^*x^*$  hold for all  $x, y$  in  $R$ . A ring equipped with an involution is called a ring with involution or  $*$ -ring. An additive mapping  $D : R \rightarrow R$  is called a  $*$ -derivation (resp. Jordan  $*$ -derivation) if  $D(xy) = D(x)y^* + xD(y)$  (resp.  $D(x^2) = D(x)x^* + xD(x)$ ) for all  $x, y$  in  $R$ . An additive mapping  $F : R \rightarrow R$  is said to be a generalized  $*$ -derivation (resp. generalized Jordan  $*$ -derivation) if there exists a  $*$ -derivation (Jordan  $*$ -derivation)  $D : R \rightarrow R$  such that  $F(xy) = F(x)y^* + xD(y)$  (resp.  $F(x^2) = F(x)x^* + xD(x)$ ) for all  $x, y$  in  $R$ .

In 2014, Rehman, et al. [11] proved that additive mappings  $F$  and  $D$ , which map an  $(n + 1)!$ -torsion free  $*$ -ring  $R$  into itself, satisfying the relation

$$F(x^{n+1}) = F(x)(x^*)^n + xD(x)(x^*)^{n-1} + \dots + x^n D(x),$$

for all  $x, y$  in  $R$ , implies  $D(x^2) = D(x)x^* + xD(x)$  and  $F(x^2) = F(x)x^* + xD(x)$  for all  $x$  in  $R$ .

This paper is inspired by the result of Rehman, et al. [11]. We generalize the notions of Jordan derivation and generalized Jordan derivation to Jordan  $(f, g)$ -derivation and generalized Jordan  $(f, g)$ -derivation respectively. Moreover, we investigate conditions for additive mappings to be Jordan  $(f, g)$ -derivation and generalized Jordan  $(f, g)$ -derivation.

## 2 Preliminaries

Throughout this paper,  $R$  will be a ring. Recall that a ring  $R$  is prime if for any  $a, b \in R$ ,  $aRb = 0$  implies  $a = 0$  or  $b = 0$ , and is semiprime if for any  $a \in R$ ,  $aRa = 0$  implies  $a = 0$ . For an integer  $n > 1$ , an element  $x \in R$  is called  $n$ -torsion free if  $nx = 0$  implies  $x = 0$ . A ring  $R$  is called an  $n$ -torsion free ring if every element in  $R$  is  $n$ -torsion free. Moreover, a ring  $R$  is called an  $n!$ -torsion free if it is  $d$ -torsion free for any divisor  $d$  of  $n!$ .

Next, we define generalizations of Jordan derivation and generalized Jordan derivation as follows:

**Definition 2.1.** *Let  $R$  be a ring and  $f, g$  be endomorphisms of  $R$ . An additive mapping  $D : R \rightarrow R$  is called a Jordan  $(f, g)$ -derivation if*

$$D(x^2) = D(x)f(x) + g(x)D(x),$$

for all  $x \in R$ .

An additive mapping  $F : R \rightarrow R$  is called a generalized Jordan  $(f, g)$ -derivation if there exists a Jordan  $(f, g)$ -derivation  $D$  such that

$$F(x^2) = F(x)f(x) + g(x)D(x),$$

for all  $x \in R$  and  $D$  is said to be an associated Jordan  $(f, g)$ -derivation of  $F$ .

Obviously, every (generalized) Jordan derivation is a (generalized) Jordan  $(f, g)$ -derivation.

## 3 Main results

**Theorem 3.1.** *Let  $n > 1$  be a fixed positive integer and let  $R$  be an  $2(n-1)!$ -torsion free ring with identity 1. If  $D : R \rightarrow R$  is an additive mapping and  $f, g$  are endomorphisms of  $R$  satisfying*

$$2D(x^n) = D(x^{n-1})f(x) + g(x^{n-1})D(x) + D(x)f(x^{n-1}) + g(x)D(x^{n-1}) \quad (3.1)$$

for all  $x \in R$ , then  $D$  is a Jordan  $(f, g)$ -derivation.

*Proof.* For  $x = 1$  in (3.1) we have  $D(1) = 0$ .

Setting  $x + k1$  for  $x$  in (3.1), where  $k$  is any positive integer, we obtain

$$\begin{aligned} 2D((x + k1)^n) &= D((x + k1)^{n-1})f(x + k1) \\ &\quad + g((x + k1)^{n-1})D(x + k1) \\ &\quad + D(x + k1)f((x + k1)^{n-1}) \\ &\quad + g(x + k1)D((x + k1)^{n-1}), \end{aligned} \quad (3.2)$$

for all  $x \in R$ .

By expanding (3.2) and using (3.1), we obtain

$$\begin{aligned} 2D\left(\sum_{i=1}^{n-1} \binom{n}{i} k^i x^{n-i}\right) &= D\left(\sum_{i=1}^{n-2} \binom{n-1}{i} k^i x^{n-1-i}\right) f(x) \\ &\quad + D\left(\sum_{i=0}^{n-2} \binom{n-1}{i} k^i x^{n-1-i}\right) kf(1) \\ &\quad + g\left(\sum_{i=1}^{n-2} \binom{n-1}{i} k^i x^{n-1-i} + k^{n-1}1\right) D(x) \\ &\quad + D(x)f\left(\sum_{i=1}^{n-2} \binom{n-1}{i} k^i x^{n-1-i} + k^{n-1}1\right) \\ &\quad + g(x)D\left(\sum_{i=1}^{n-2} \binom{n-1}{i} k^i x^{n-1-i}\right) \\ &\quad + kg(1)D\left(\sum_{i=0}^{n-2} \binom{n-1}{i} k^i x^{n-1-i}\right). \end{aligned}$$

This can be written as

$$kh_1(x, 1) + k^2h_2(x, 1) + \cdots + k^{n-1}h_{n-1}(x, 1) = 0,$$

for all  $x \in R$ , where  $h_i(x, 1)$  are the coefficients of  $k^i$  for all  $i = 1, 2, \dots, n-1$ . Replacing  $k$  by  $1, 2, \dots, n-1$ , and expressing the resulting system of  $n-1$  homogeneous equations, we get

$$AH = [0],$$

$$\text{where } A = \begin{bmatrix} 1 & 1^2 & \cdots & 1^{n-1} \\ 2 & 2^2 & \cdots & 2^{n-1} \\ \vdots & \vdots & \ddots & \vdots \\ n-1 & (n-1)^2 & \cdots & (n-1)^{n-1} \end{bmatrix},$$

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$$H = \begin{bmatrix} h_1(x, 1) \\ h_2(x, 1) \\ \vdots \\ h_{n-1}(x, 1) \end{bmatrix} \text{ and } [0] \text{ is } (n-1) \times 1 \text{ zero matrix.}$$

Since  $\det(A) = \prod_{i=0}^{n-2} (n-i)!$  and  $R$  is  $2(n-1)!$ -torsion free, it follows that the system has only a trivial solution. In particular,  $h_{n-2}(x, 1) = 0$  implies that

$$2(n-1)D(x^2) = 2(n-1)D(x)f(x) + 2(n-1)g(x)D(x),$$

for all  $x \in R$ . Since  $R$  is  $2(n-1)!$ -torsion free, it follows that

$$D(x^2) = D(x)f(x) + g(x)D(x),$$

for all  $x \in R$ .

Therefore,  $D$  is a Jordan  $(f, g)$ -derivation.  $\square$

**Theorem 3.2.** *Let  $R$  be a 2-torsion free semiprime ring. Let  $f : R \rightarrow R$  be a homomorphism and  $g : R \rightarrow R$  be an epimorphism. If  $D : R \rightarrow R$  is an additive mapping satisfying*

$$D(xy) = D(x)f(y) + g(y)D(x), \quad (3.3)$$

for all  $x, y \in R$ , then  $D$  is a Jordan  $(f, g)$ -derivation.

*Proof.* Linearization of the equation (3.3) gives

$$D(xyz + zyx) = D(xy)f(z) + D(zx)f(y) + g(yz)D(x) + g(zx)D(y),$$

for all  $x, y, z \in R$ . In particular, for  $z = x^2$ , the above equation gives

$$\begin{aligned} D(xy x^2 + x^2 yx) &= D(xy)f(x^2) + D(x^2 y)f(x) \\ &\quad + g(yx^2)D(x) + g(x^2 y)D(x), \end{aligned} \quad (3.4)$$

for all  $x, y \in R$ .

Replacing  $y$  by  $xy + yx$  in (3.3) and using (3.3), we get

$$\begin{aligned} D(x^2 yx + xy x^2) &= D(x^2 y)f(x) + D(xy)f(x^2) + g(yx^2)D(x) \\ &\quad + g(x^2 y)D(x) + g(xy x)D(x), \end{aligned} \quad (3.5)$$

for all  $x, y \in R$ . By comparing (3.4) and (3.5), we have

$$g(x)g(y)A(x) = 0 \text{ for all } x, y \in R, \quad (3.6)$$

where  $A(x) = D(x^2) - D(x)f(x) - g(x)D(x)$ .

Since  $g$  is onto, the equation (3.6) can be written

$$g(x)yA(x) = 0 \text{ for all } x, y \in R. \quad (3.7)$$

Right multiplication of (3.7) by  $g(x)$  and left multiplication by  $A(x)$  yield

$$A(x)g(x)yA(x)g(x) = 0 \text{ for all } x, y \in R.$$

By the semiprimeness of  $R$ , it follows that

$$A(x)g(x) = 0 \text{ for all } x \in R. \quad (3.8)$$

Replacing  $y$  by  $A(x)y$  in (3.7), we have

$$g(x)A(x)yA(x) = 0 \text{ for all } x, y \in R.$$

Again, by the semiprimeness of  $R$ , we have

$$g(x)A(x) = 0 \text{ for all } x \in R. \quad (3.9)$$

The linearizing of (3.8) gives

$$B(x, y)g(x) + A(x)g(y) + B(x, y)g(y) + A(x)g(x) = 0, \quad (3.10)$$

for all  $x, y \in R$ , where

$$B(x, y) = D(xy + yx) - D(x)f(y) - D(y)f(x) - g(x)D(y) - g(y)D(x).$$

The substitution  $-x$  for  $x$  in (3.10) leads to

$$B(x, y)g(x) + A(x)g(y) - B(x, y)g(y) - A(y)g(x) = 0, \quad (3.11)$$

for all  $x, y \in R$ . The equations (3.10) and (3.11) reduce to

$$2(B(x, y)g(x) + A(x)g(y)) = 0, \text{ for all } x, y \in R.$$

Since  $R$  is 2-torsion free, it follows that

$$B(x, y)g(x) + A(x)g(y) = 0 \text{ for all } x, y \in R.$$

In view of the equation (3.9), right multiplication by  $A(x)$  yields  $A(x)g(y)A(x) = 0$ , for all  $x, y \in R$ . Since  $g$  is onto and  $R$  is semiprime, it follows that

$$A(x) = 0, \text{ for all } x \in R.$$

Hence  $D(x^2) = D(x)f(x) + g(x)D(x)$ , for all  $x \in R$ .

In other words,  $D$  is a Jordan  $(f, g)$ -derivation.  $\square$

For the sake of brevity, we omit the proof of the following theorem.

**Theorem 3.3.** *Let  $R$  be a 2-torsion free semiprime ring. Let  $f : R \rightarrow R$  be an epimorphism and  $g : R \rightarrow R$  be a homomorphism. If  $D : R \rightarrow R$  is an additive mapping satisfying*

$$D(xy) = D(x)f(y) + g(x)D(y),$$

for all  $x, y \in R$ , then  $D$  is a Jordan  $(f, g)$ -derivation.

Let  $f$  and  $g$  be endomorphisms of a ring  $R$ . If  $F : R \rightarrow R$  and  $D : R \rightarrow R$  are additive mappings satisfying

$$F(x^{n+1}) = F(x)f(x^n) + \sum_{i=1}^n g(x^i)D(x)f(x^{n-i}), \quad (3.12)$$

for all  $x \in R$ . It is natural to ask the additive mappings satisfying (3.12) implies that

$$F(x^2) = F(x)f(x) + g(x)D(x) \text{ and } D(x^2) = D(x)f(x) + g(x)D(x),$$

for all  $x \in R$ .

**Theorem 3.4.** *Let  $n$  be a fixed positive integer and let  $R$  be an  $(n+1)!$ -torsion free ring with identity 1. If  $F : R \rightarrow R, D : R \rightarrow R$  are two additive mappings and  $f, g$  are endomorphisms of  $R$  satisfying*

$$F(x^{n+1}) = F(x)f(x^n) + \sum_{i=1}^n g(x^i)D(x)f(x^{n-i}), \quad (3.13)$$

for all  $x \in R$ , then  $D$  is a Jordan  $(f, g)$ -derivation on  $R$  and  $F$  is a generalized Jordan  $(f, g)$ -derivation.

*Proof.* Taking  $x = 1$  in (3.13), we obtain  $F(1) = F(1) + nD(1)$ .

This implies that  $nD(1) = 0$  and since  $R$  is  $(n+1)!$ -torsion free, we get  $D(1) = 0$ . Replacing  $x$  by  $x + k1$  in (3.13), where  $k$  is any positive integer, we obtain

$$F((x + k1)^{n+1}) = (F(x) + kF(1))(f(x) + k1)^n + \sum_{i=1}^n (g(x) + k1)^i D(x)(f(x) + k1)^{n-i}, \quad (3.14)$$

for all  $x \in R$ .

By expanding (3.14) and using (3.13), we obtain

$$\begin{aligned}
F\left(\sum_{i=1}^n \binom{n+1}{i} k^i x^{n+1-i}\right) &= F(x) \left(\sum_{i=1}^{n-1} \binom{n}{i} k^i f(x^{n-i}) + k^n \mathbf{1}\right) \\
&\quad + kF(1) \left(\sum_{i=1}^{n-1} \binom{n}{i} k^i f(x^{n-i})\right) \\
&\quad + g(x)D(x) \left(\sum_{i=1}^{n-2} \binom{n-1}{i} k^i f(x^{n-i}) + k^{n-1} \mathbf{1}\right) \\
&\quad + kD(x) \left(\sum_{i=0}^{n-2} \binom{n-i}{i} k^i f(x^{n-1-i}) + k^{n-1} \mathbf{1}\right) \\
&\quad + g(x^2)D(x) \left(\sum_{i=1}^{n-3} \binom{n-2}{i} k^i f(x^{n-2-i}) + k^{n-2} \mathbf{1}\right) \\
&\quad + 2kg(x)D(x) \left(\sum_{i=0}^{n-3} \binom{n-2}{i} k^i f(x^{n-2-i}) + k^{n-2} \mathbf{1}\right) \\
&\quad + k^2D(x) \left(\sum_{i=0}^{n-3} \binom{n-2}{i} k^i f(x^{n-2-i}) + k^{n-2} \mathbf{1}\right) \\
&\quad \vdots \\
&\quad + \left(\sum_{i=1}^{n-2} \binom{n-1}{i} k^i g(x^{n-1-i}) + k^{n-1} \mathbf{1}\right) D(x)f(x) \\
&\quad + \left(\sum_{i=1}^{n-2} \binom{n-1}{i} k^i g(x^{n-1-i}) + k^{n-1} \mathbf{1}\right) kD(x) \\
&\quad + \left(\sum_{i=1}^{n-1} \binom{n}{i} k^i g(x^{n-i}) + k^n \mathbf{1}\right) D(x).
\end{aligned}$$

Collecting terms, we obtain

$$kh_1(x, 1) + k^2h_2(x, 1) + \cdots + k^nh_n(x, 1) = 0,$$

for all  $x \in R$ , where  $h_i(x, 1)$  are the coefficients of  $k^i$  for all  $i = 1, 2, \dots, n$ . Replacing  $k$  by  $1, 2, \dots, n$ , and expressing the resulting system of  $n$  homogeneous equations, we get

$$AH = [0],$$



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$$\text{where } A = \begin{bmatrix} 1 & 1^2 & \cdots & 1^n \\ 2 & 2^2 & \cdots & 2^n \\ \vdots & \vdots & \ddots & \vdots \\ n & n^2 & \cdots & n^n \end{bmatrix},$$

$$H = \begin{bmatrix} h_1(x, 1) \\ h_2(x, 1) \\ \vdots \\ h_n(x, 1) \end{bmatrix} \text{ and } [0] \text{ is } n \times 1 \text{ zero matrix.}$$

Since  $\det(A) = \prod_{i=0}^{n-1} (n-i)!$ , and  $R$  is  $(n+1)!$ -torsion free ring, it follows that the system has only a trivial solution. In particular,  $h_n(x, 1) = 0$  implies that  $(n+1)F(x) = F(x) + nF(1)f(x) + nD(x)$  for all  $x \in R$ . Since  $R$  is  $(n+1)!$ -torsion free, we get

$$F(x) = F(1)f(x) + D(x) \text{ for all } x \in R.$$

Next,  $h_{n-1}(x, 1) = 0$  implies that

$$\begin{aligned} n(n+1)F(x^2) &= 2nF(x)f(x) + n(n-1)F(1)f(x^2) + n(n+1)g(x)D(x) \\ &\quad + n(n-1)D(x)f(x) \text{ for all } x \in R. \end{aligned}$$

Using  $F(x) = F(1)f(x) + D(x)$  and  $R$  is  $(n+1)!$ -torsion free. The above equation reduces to

$$F(x^2) = F(1)f(x^2) + D(x)f(x) + g(x)D(x) \quad (3.15)$$

for all  $x \in R$ . Replacing  $x$  by  $x^2$  in  $F(x) = F(1)f(x) + D(x)$ , yields

$$F(x^2) = F(1)f(x^2) + D(x^2) \text{ for all } x \in R. \quad (3.16)$$

Equating (3.15) and (3.16), we have

$$D(x^2) = D(x)f(x) + g(x)D(x) \text{ for all } x \in R.$$

Thus,  $D$  is a Jordan  $(f, g)$ -derivation on  $R$ . Now, by (3.15) and using  $F(x) = F(1)f(x) + D(x)$ , we get

$$F(x^2) = F(x)f(x) + g(x)D(x) \text{ for all } x \in R.$$

Hence,  $F$  is a generalized Jordan  $(f, g)$ -derivation.

The proof of the theorem is complete.  $\square$

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