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## On characterizations of $\delta p(\Lambda, s)$ - $\mathcal{D}_1$ spaces

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#### Abstract

Our main purpose is to introduce the concept of  $\delta p(\Lambda, s)$ - $\mathcal{D}_1$  spaces. Moreover, some characterizations of  $\delta p(\Lambda, s)$ - $\mathcal{D}_1$  spaces are investigated.

### 1 Introduction

In 1968, Veličko [8] introduced  $\delta$ -open sets, which are stronger than open sets. In 1982, Mashhour et al. [6] introduced and investigated the notion of preopen sets which is weaker than the notion of open sets in topological spaces. In 1993, Raychaudhuri and Mukherjee [7] introduced and studied the notions of  $\delta$ -preopen sets and  $\delta$ -almost continuity in topological spaces. The class of  $\delta$ -preopen sets is larger than that of preopen sets. In 2005, Caldas et al. [2] introduced some weak separation axioms by utilizing the notions of  $\delta$ -preopen sets and the  $\delta$ -preclosure operator. The concept of semi-open sets was first introduced by Levine [5]. Caldas and Dontchev [4] introduced and investigated the notion of  $\Lambda_s$ -sets in topological spaces. Moreover, Caldas et al. [3] studied further the notion of  $\delta$ - $\Lambda_s$ -semiclosed sets which is defined as the intersection of a  $\delta$ - $\Lambda_s$ -set and a  $\delta$ -semiclosed set. In [1], the present

Key words and phrases:  $\delta p(\Lambda, s)$ -open set,  $\delta p(\Lambda, s)$ - $\mathscr{D}_1$  space. Corresponding author: Napassanan Srisarakham. AMS (MOS) Subject Classifications: 54A05, 54D10. ISSN 1814-0432, 2023, http://ijmcs.future-in-tech.net authors introduced and studied the notion of  $(\Lambda, s)$ -closed sets by utilizing the notions of  $\Lambda_s$ -sets and semi-closed sets. In this paper, we introduced the concept of  $\delta p(\Lambda, s)$ - $\mathscr{D}_1$  spaces. Moreover, several characterizations of  $\delta p(\Lambda, s)$ - $\mathscr{D}_1$  spaces are discussed.

### 2 Preliminaries

Throughout the present paper, unless explicitly stated, spaces  $(X, \tau)$  and  $(Y,\sigma)$  (or simply X and Y) always mean topological spaces on which no separation axioms are assume . Let A be a subset of a topological space  $(X,\tau)$ . The closure of A and the interior of A are denoted by Cl(A) and Int(A), respectively. A subset A of a topological space  $(X, \tau)$  is called *semi*open [5] if  $A \subset Cl(Int(A))$ . The complement of a semi-open set is called *semi*closed. The family of all semi-open (resp. semi-closed) sets in a topological space  $(X, \tau)$  is denoted by  $SO(X, \tau)$  (resp.  $SC(X, \tau)$ ). A subset  $A^{\Lambda_s}$  (resp.  $A^{V_s}$  [2] is defined as follows:  $A^{\Lambda_s} = \bigcap \{ U \mid U \supseteq A, U \in SO(X, \tau) \}$  (resp.  $A^{V_s} = \bigcup \{F \mid F \subseteq A, F \in SC(X, \tau)\}$ ). A subset A of a topological space  $(X,\tau)$  is called a  $\Lambda_s$ -set (resp.  $V_s$ -set) [2] if  $A = A^{\Lambda_s}$  (resp.  $A = A^{V_s}$ ). A subset A of a topological space  $(X, \tau)$  is called  $(\Lambda, s)$ -closed [1] if A = $T \cap C$ , where T is a  $\Lambda_s$ -set and C is a semi-closed set. The complement of a  $(\Lambda, s)$ -closed set is called  $(\Lambda, s)$ -open. The family of all  $(\Lambda, s)$ -closed (resp.  $(\Lambda, s)$ -open) sets in a topological space  $(X, \tau)$  is denoted by  $\Lambda_s C(X, \tau)$  (resp.  $\Lambda_s O(X,\tau)$ ). Let A be a subset of a topological space  $(X,\tau)$ . A point  $x \in X$ is called a  $(\Lambda, s)$ -cluster point [1] of A if for every  $(\Lambda, s)$ -open set U of X containing x we have  $A \cap U \neq \emptyset$ . The set of all  $(\Lambda, s)$ -cluster points of A is called the  $(\Lambda, s)$ -closure [1] of A and is denoted by  $A^{(\Lambda,s)}$ . The union of all  $(\Lambda, s)$ -open sets contained in A is called the  $(\Lambda, s)$ -interior [1] of A and is denoted by  $A_{(\Lambda,s)}$ .

# **3** $\delta p(\Lambda, s)$ - $\mathscr{D}_1$ spaces

We introduce the notion of  $\delta p(\Lambda, s)$ - $\mathcal{D}_1$  spaces. Moreover, some characterizations of  $\delta p(\Lambda, s)$ - $\mathcal{D}_1$  spaces are discussed.

**Definition 3.1.** Let A be a subset of a topological space  $(X, \tau)$ . A point x of X is called a  $\delta(\Lambda, s)$ -cluster point of A if  $A \cap [V^{(\Lambda,s)}]_{(\Lambda,s)} \neq \emptyset$  for every  $(\Lambda, s)$ -open set V of X containing x. The set of all  $\delta(\Lambda, s)$ -cluster points of A is called the  $\delta(\Lambda, s)$ -closure of A and is denoted by  $A^{\delta(\Lambda,s)}$ . If  $A = A^{\delta(\Lambda,s)}$ , On characterizations of  $\delta p(\Lambda, s)$ - $\mathcal{D}_1$  spaces

then A is said to be  $\delta(\Lambda, s)$ -closed. The complement of a  $\delta(\Lambda, s)$ -closed set is said to be  $\delta(\Lambda, s)$ -open.

Let A be a subset of a topological space  $(X, \tau)$ . The union of all  $\delta(\Lambda, s)$ open sets contained in A is called the  $\delta(\Lambda, s)$ -interior of A and is denoted by  $A_{\delta(\Lambda,s)}$ .

**Definition 3.2.** A subset A of a topological space  $(X, \tau)$  is said to be  $\delta p(\Lambda, s)$ open if  $A \subseteq [A^{(\Lambda,s)}]_{\delta(\Lambda,s)}$ . The complement of a  $\delta p(\Lambda, s)$ -open set is said to
be  $\delta p(\Lambda, s)$ -closed.

The family of all  $\delta p(\Lambda, s)$ -open (resp.  $\delta p(\Lambda, s)$ -closed) sets in a topological space  $(X, \tau)$  is denoted by  $\delta p(\Lambda, s)O(X, \tau)$  (resp.  $\delta p(\Lambda, s)C(X, \tau)$ ). Let A be a subset of a topological space  $(X, \tau)$ . The intersection of all  $\delta p(\Lambda, s)$ -closed sets containing A is called the  $\delta p(\Lambda, s)$ -closure of A and is denoted by  $A^{\delta p(\Lambda, s)}$ .

**Lemma 3.3.** For the  $\delta p(\Lambda, s)$ -closure of subsets A, B in a topological space  $(X, \tau)$ , the following properties hold:

- (1) If  $A \subseteq B$ , then  $A^{\delta p(\Lambda,s)} \subseteq B^{\delta p(\Lambda,s)}$ .
- (2) A is  $\delta p(\Lambda, s)$ -closed in  $(X, \tau)$  if and only if  $A = A^{\delta p(\Lambda, s)}$ .
- (3)  $A^{\delta p(\Lambda,s)}$  is  $\delta p(\Lambda,s)$ -closed, that is,  $A^{\delta p(\Lambda,s)} = [A^{\delta p(\Lambda,s)}]^{\delta p(\Lambda,s)}$ .
- (4)  $x \in A^{\delta p(\Lambda,s)}$  if and only if  $A \cap V \neq \emptyset$  for every  $V \in \delta p(\Lambda,s)O(X,\tau)$  containing x.

**Lemma 3.4.** For a family  $\{A_{\gamma} \mid \gamma \in \nabla\}$  of a topological space  $(X, \tau)$ , the following properties hold:

- (1)  $[\cap \{A_{\gamma} \mid \gamma \in \nabla\}]^{\delta p(\Lambda,s)} \subseteq \cap \{A_{\gamma}^{\delta p(\Lambda,s)} \mid \gamma \in \nabla\}.$
- $(2) \ [\cup\{A_{\gamma} \mid \gamma \in \nabla\}]^{\delta p(\Lambda,s)} \supseteq \cup\{A_{\gamma}^{\delta p(\Lambda,s)} \mid \gamma \in \nabla\}.$

**Definition 3.5.** A subset  $N_x$  of a topological space  $(X, \tau)$  is said to be a  $\delta p(\Lambda, s)$ -neighborhood of a point  $x \in X$  if there exists a  $\delta p(\Lambda, s)$ -open set U such that  $x \in U \subseteq N_x$ .

**Definition 3.6.** Let  $(X, \tau)$  be a topological space. A point  $x \in X$  which has only X as the  $\delta p(\Lambda, s)$ -neighborhood is called a  $\delta p(\Lambda, s)$ -neat point.

**Lemma 3.7.** Let  $(X, \tau)$  be a topological space. For each point  $x \in X$ ,  $\{x\}$  is  $p(\Lambda, s)$ -open or  $p(\Lambda, s)$ -closed.

**Lemma 3.8.** Let A be a subset of a topological space  $(X, \tau)$ . If A is  $p(\Lambda, s)$ -open in  $(X, \tau)$ , then A is  $\delta p(\Lambda, s)$ -open in  $(X, \tau)$ .

**Definition 3.9.** A subset A of a topological space  $(X, \tau)$  is called a  $\delta p(\Lambda, s)\mathcal{D}$ set if there exist  $\delta p(\Lambda, s)$ -open sets U and V such that  $U \neq X$  and A = U - V.

**Definition 3.10.** A topological space  $(X, \tau)$  is said to be  $\delta p(\Lambda, s)$ - $\mathcal{D}_1$  if, for any distinct pair of points x and y of X, there exist a  $\delta p(\Lambda, s)\mathcal{D}$ -set U of X containing x but not y and a  $\delta p(\Lambda, s)\mathcal{D}$ -set V of X containing y but not x.

**Theorem 3.11.** For a topological space  $(X, \tau)$ , the following properties are equivalent:

- (1)  $(X, \tau)$  is  $\delta p(\Lambda, s)$ - $\mathcal{D}_1$ ;
- (2)  $(X, \tau)$  has no  $\delta p(\Lambda, s)$ -neat point.

Proof. (1)  $\Rightarrow$  (2): Since  $(X, \tau)$  is  $\delta p(\Lambda, s) \cdot \mathscr{D}_1$ , each point x of X is contained in a  $\delta p(\Lambda, s) \mathscr{D}$ -set G = U - V and thus in U, where U and V are  $\delta p(\Lambda, s)$ open sets. By definition  $U \neq X$ . This implies that x is not a  $\delta p(\Lambda, s)$ -neat point.

(2)  $\Rightarrow$  (1): By Lemma 3.7, for each distinct pair of points  $x, y \in X$ , at least one of them, x (say) has a  $\delta p(\Lambda, s)$ -neighborhood U containing x and not y. Thus U which is different from X is a  $\delta p(\Lambda, s)$   $\mathscr{D}$ -set. If X has no  $\delta p(\Lambda, s)$ neat point, then y is not a  $\delta p(\Lambda, s)$ -neat point. This means that there exists a  $\delta p(\Lambda, s)$ -neighborhood V of y such that  $V \neq X$ . Thus  $y \in V - U$  but not y and V - U is a  $\delta p(\Lambda, s) \mathscr{D}$ -set. This shows that  $(X, \tau)$  is  $\delta p(\Lambda, s) \cdot \mathscr{D}_1$ .  $\Box$ 

**Definition 3.12.** A function  $f : (X, \tau) \to (Y, \sigma)$  is called  $\delta p(\Lambda, s)$ -continuous if, for each  $x \in X$  and each  $\delta p(\Lambda, s)$ -open set V of Y containing f(x), there exists a  $\delta p(\Lambda, s)$ -open set U of X containing x such that  $f(U) \subseteq V$ .

**Lemma 3.13.** A function  $f : (X, \tau) \to (Y, \sigma)$  is  $\delta p(\Lambda, s)$ -continuous if and only if  $f^{-1}(V)$  is  $\delta p(\Lambda, s)$ -open in X for every  $\delta p(\Lambda, s)$ -open set V of Y.

**Theorem 3.14.** If  $f : (X, \tau) \to (Y, \sigma)$  is a  $\delta p(\Lambda, s)$ -continuous surjective function and B is a  $\delta p(\Lambda, s) \mathscr{D}$ -set in Y, then  $f^{-1}(B)$  is a  $\delta p(\Lambda, s) \mathscr{D}$ -set in X.

Proof. Let B be a  $\delta p(\Lambda, s) \mathscr{D}$ -set in Y. Then, there exist  $\delta p(\Lambda, s)$ -open sets U and V in Y such that B = U - V and  $U \neq Y$ . By the  $\delta p(\Lambda, s)$ -continuity of f,  $f^{-1}(U)$  and  $f^{-1}(V)$  are  $\delta p(\Lambda, s)$ -open in X. Since  $U \neq Y$ , we have  $f^{-1}(U) \neq X$ . Thus  $f^{-1}(B) = f^{-1}(U) - f^{-1}(V)$  is a  $\delta p(\Lambda, s) \mathscr{D}$ -set.  $\Box$ 

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**Theorem 3.15.** If  $(Y, \sigma)$  is a  $\delta p(\Lambda, s)$ - $\mathscr{D}_1$  space and  $f : (X, \tau) \to (Y, \sigma)$  is a  $\delta p(\Lambda, s)$ -continuous bijection, then  $(X, \tau)$  is  $\delta p(\Lambda, s)$ - $\mathscr{D}_1$ .

Proof. Suppose that  $(Y, \sigma)$  is a  $\delta p(\Lambda, s) - \mathscr{D}_1$  space. Let x and y be any pair of distinct points in X. Since f is injective and  $(Y, \sigma)$  is  $\delta p(\Lambda, s) - \mathscr{D}_1$ , there exist  $\delta p(\Lambda, s) \mathscr{D}$ -sets U and V of Y containing f(x) and f(y), respectively, such that  $f(y) \notin U$  and  $f(x) \notin V$ . By Theorem 3.14,  $f^{-1}(U)$  and  $f^{-1}(V)$  are  $\delta p(\Lambda, s) \mathscr{D}$ -sets in X containing x and y, respectively, such that  $y \notin f^{-1}(U)$ and  $x \notin f^{-1}(V)$ . This shows that  $(X, \tau)$  is  $\delta p(\Lambda, s) - \mathscr{D}_1$ .

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