

On characterizations of $S\Lambda_s-T_2$ spaces

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Abstract

Our main purpose is to introduce the concept of $S\Lambda_s-T_2$ spaces. Moreover, we investigate some characterizations of $S\Lambda_s-T_2$ spaces.

1 Introduction

Veličko [9] introduced δ -open sets, which are stronger than open sets. Park et al. [5] have offered a new notion called δ -semiopen sets which are stronger than semi-open sets but weaker than δ -open sets and investigated the relationships among several types of these open sets. Caldas et al. [4] investigated some weak separation axioms by utilizing δ -semiopen sets and the δ -semiclosure operator. Caldas et al. [3] investigated the notion of δ - Λ_s -semiclosed sets which is defined as the intersection of a δ - Λ_s -set and a δ -semiclosed set. In [1], the present authors introduced and investigated the concept of (Λ, s) -closed sets by utilizing the notions of Λ_s -sets and semi-closed sets. Pue-on and Boonpok [6] introduced and investigated the notions of $\delta s(\Lambda, s)$ -open sets and $\delta s(\Lambda, s)$ -closed sets. Srisarakham and Boonpok [8] introduced and studied the concept of $\delta p(\Lambda, s)-\mathcal{D}_1$ spaces. Buadong et al.

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[2] investigated some characterizations of T_1 -GTMS spaces and T_2 -GTMS spaces. In this paper, we introduce the concept of $S\Lambda_s$ - T_2 spaces. Moreover, we discuss several characterizations of $S\Lambda_s$ - T_2 spaces.

2 Preliminaries

A subset A of a topological space (X, τ) is called (Λ, s) -closed [1] if $A = T \cap C$, where T is a Λ_s -set and C is a semi-closed set. The complement of a (Λ, s) -closed set is called (Λ, s) -open. A subset A of a topological space (X, τ) is called $s(\Lambda, s)$ -open [1] if $A \subseteq [A_{(\Lambda, s)}]^{(\Lambda, s)}$. The family of all $s(\Lambda, s)$ -open sets in a topological space (X, τ) is denoted by $s(\Lambda, s)O(X, \tau)$. The complement of a $s(\Lambda, s)$ -open set is called $s(\Lambda, s)$ -closed. Let A be a subset of a topological space (X, τ) . The intersection of all $s(\Lambda, s)$ -closed sets containing A is called the $s(\Lambda, s)$ -closure [7] of A and is denoted by $A^{s(\Lambda, s)}$. A subset A is said to be $s(\Lambda, s)$ -regular [7] if A is $s(\Lambda, s)$ -open and $s(\Lambda, s)$ -closed. The family of all $s(\Lambda, s)$ -regular sets in a topological space (X, τ) is denoted by $s(\Lambda, s)r(X, \tau)$. A point x of X is called a $\delta(\Lambda, s)$ -cluster point [8] of A if $A \cap [U^{(\Lambda, s)}]_{(\Lambda, s)} \neq \emptyset$ for every (Λ, s) -open set U of X containing x . The set of all $\delta(\Lambda, s)$ -cluster points of A is called the $\delta(\Lambda, s)$ -closure [8] of A and is denoted by $A^{\delta(\Lambda, s)}$. A subset A is called $\delta(\Lambda, s)$ -closed [8] if $A = A^{\delta(\Lambda, s)}$. The complement of a $\delta(\Lambda, s)$ -closed set is said to be $\delta(\Lambda, s)$ -open. A subset A is called $\delta s(\Lambda, s)$ -open [6] if $A \subseteq [A_{(\Lambda, s)}]^{\delta(\Lambda, s)}$. The complement of a $\delta s(\Lambda, s)$ -open set is called $\delta s(\Lambda, s)$ -closed. The family of all $\delta s(\Lambda, s)$ -open sets in a topological space (X, τ) is denoted by $\delta s(\Lambda, s)O(X, \tau)$. A point x of X is called a $\delta s(\Lambda, s)$ -cluster point [6] of A if $A \cap U \neq \emptyset$ for every $\delta s(\Lambda, s)$ -open set U of X containing x . The set of all $\delta s(\Lambda, s)$ -cluster points of A is called the $\delta s(\Lambda, s)$ -closure [6] of A and is denoted by $A^{\delta s(\Lambda, s)}$.

3 Characterizations of $S\Lambda_s$ - T_2 spaces

In this section, we introduce the concept of $S\Lambda_s$ - T_2 spaces. Moreover, we discuss some characterizations of $S\Lambda_s$ - T_2 spaces.

Definition 3.1. *A topological space (X, τ) is said to be $S\Lambda_s$ - T_2 if, for each pair of distinct points $x, y \in X$, there exist $U, V \in s(\Lambda, s)O(X, \tau)$ such that $x \in U$, $y \in V$ and $U \cap V = \emptyset$.*

Lemma 3.2. [7] *For a subset A of a topological space (X, τ) , the following properties hold:*

- (1) If A is a $s(\Lambda, s)$ -regular set, then it is $\delta s(\Lambda, s)$ -open.
- (2) If A is a $\delta s(\Lambda, s)$ -open set, then it is $s(\Lambda, s)$ -open.
- (3) If A is a $s(\Lambda, s)$ -open set, then $A^{s(\Lambda, s)}$ is $s(\Lambda, s)$ -regular.

Theorem 3.3. For a topological space (X, τ) , the following properties are equivalent:

- (1) (X, τ) is $S\Lambda_s-T_2$;
- (2) For each pair of distinct points x, y of X , there exist $U, V \in s(\Lambda, s)r(X, \tau)$ such that $x \in U, y \in V$ and $U \cap V = \emptyset$.
- (3) For each pair of distinct points x, y of X , there exist $U, V \in \delta s(\Lambda, s)O(X, \tau)$ such that $x \in U, y \in V$ and $U^{\delta s(\Lambda, s)} \cap V^{\delta s(\Lambda, s)} = \emptyset$.
- (4) For each pair of distinct points x, y of X , there exist $U, V \in \delta s(\Lambda, s)O(X, \tau)$ such that $x \in U, y \in V$ and $U^{s(\Lambda, s)} \cap V^{s(\Lambda, s)} = \emptyset$.
- (5) For each pair of distinct points x, y of X , there exist $U, V \in \delta s(\Lambda, s)O(X, \tau)$ such that $x \in U, y \in V$ and $U \cap V = \emptyset$.

Proof. (1) \Rightarrow (2): Suppose that (X, τ) is $S\Lambda_s-T_2$. Then, for each pair of distinct points x, y of X , there exist $G, H \in s(\Lambda, s)O(X, \tau)$ such that $x \in G, y \in H$ and $G \cap H = \emptyset$. Thus, $G^{s(\Lambda, s)} \cap H = \emptyset$. By Lemma 3.2, we have $G^{s(\Lambda, s)} \in s(\Lambda, s)r(X, \tau)$ and $G^{s(\Lambda, s)} \cap H^{s(\Lambda, s)} = \emptyset$. Now set $U = G^{s(\Lambda, s)}$ and $V = H^{s(\Lambda, s)}$. Then, U and V are $s(\Lambda, s)$ -regular sets such that $x \in U, y \in V$ and $U \cap V = \emptyset$.

(2) \Rightarrow (3): This follows from the facts that $s(\Lambda, s)r(X, \tau) \subseteq \delta s(\Lambda, s)O(X, \tau)$ and $U^{\delta s(\Lambda, s)} = U^{s(\Lambda, s)} = U$ for every $U \in s(\Lambda, s)r(X, \tau)$.

(3) \Rightarrow (4): This follows from the fact that $U^{\delta s(\Lambda, s)} = U^{s(\Lambda, s)}$ for every $U \in \delta s(\Lambda, s)O(X, \tau)$.

(4) \Rightarrow (5): This is obvious.

(5) \Rightarrow (1): This is obvious since $\delta s(\Lambda, s)O(X, \tau) \subseteq s(\Lambda, s)O(X, \tau)$. \square

Definition 3.4. A topological space (X, τ) is said to be $S\Lambda_s$ -Urysohn if, for each pair of distinct points x, y of X , there exist $U, V \in s(\Lambda, s)O(X, \tau)$ such that $x \in U, y \in V$ and $U^{(\Lambda, s)} \cap V^{(\Lambda, s)} = \emptyset$.

Theorem 3.5. A topological space (X, τ) is $S\Lambda_s$ -Urysohn if and only if for each pair of distinct points x, y of X , there exist $U, V \in \delta s(\Lambda, s)O(X, \tau)$ such that $x \in U, y \in V$ and $U^{(\Lambda, s)} \cap V^{(\Lambda, s)} = \emptyset$.

Proof. Necessity. Suppose that (X, τ) is $S\Lambda_s$ -Urysohn. Then, for each pair of distinct points x, y of X , there exist $U, V \in s(\Lambda, s)O(X, \tau)$ such that $x \in U, y \in V$ and $U^{(\Lambda, s)} \cap V^{(\Lambda, s)} = \emptyset$. Since $U \in s(\Lambda, s)O(X, \tau)$, $U^{(\Lambda, s)} = [U_{(\Lambda, s)}]^{(\Lambda, s)}$ and $U^{(\Lambda, s)}$ is $r(\Lambda, s)$ -closed. Thus, $U^{(\Lambda, s)}, V^{(\Lambda, s)} \in s(\Lambda, s)r(X, \tau) \subseteq \delta s(\Lambda, s)O(X, \tau)$. It is obvious that $x \in U^{(\Lambda, s)}, y \in V^{(\Lambda, s)}$ and

$$[U^{(\Lambda, s)}]^{(\Lambda, s)} \cap [V^{(\Lambda, s)}]^{(\Lambda, s)} = U^{(\Lambda, s)} \cap V^{(\Lambda, s)} = \emptyset.$$

Sufficiency. The proof is obvious since $\delta s(\Lambda, s)O(X, \tau) \subseteq s(\Lambda, s)O(X, \tau)$. \square

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